

TACTICAL ROBOTIC FLEET CONTROL

NOMAD

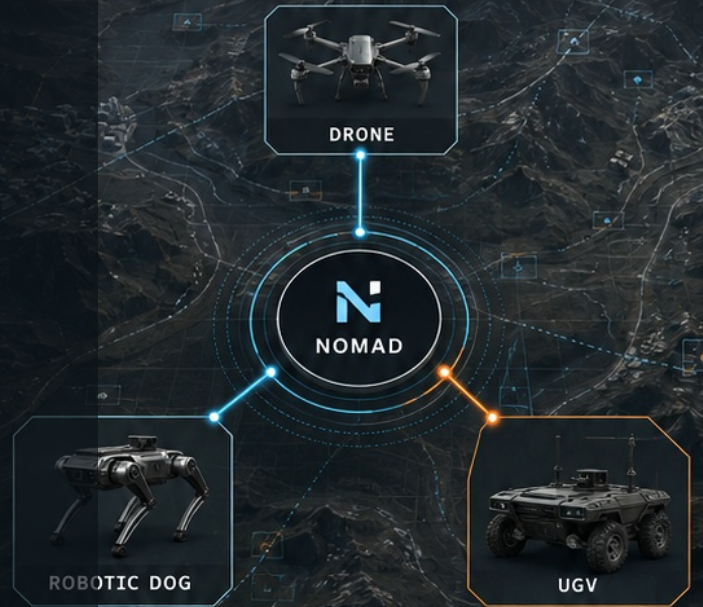
ONE CONTROL PLANE FOR MIXED DRONE, ROBOTIC DOG & UGV FLEETS

NOMAD unifies heterogeneous robotic platforms, sensors and mission feeds into one tactical control plane. One operator picture. Any platform. Any environment.

PROTOCOL
TRANSLATION

MIXED FLEETS

EDGE DEPLOYED



UNIFIED FLEET ARCHITECTURE

DRONE

ROBOTIC DOG

UGV

NOMAD CONTROL PLANE

ROS2 | MAVLink | ATAK / CoT | STANAG 4609



UNIFIED CONTROL PLANE

One operator picture across mixed robotic fleets and vendors.



SHARED OPERATIONAL PICTURE

Video, telemetry, tracks and mission status in one view.



TASKING & MISSION CONTROL

Assign missions, maintain audit trail and coordinate mixed fleets.



MESH / DEGRADED OPS

Maintain command and control with resilient disconnected operation.

OPEN INTEGRATION

WORKS WITH YOUR EXISTING PLATFORMS AND C2 SOFTWARE

Integrate third-party platforms and mission systems without replacing what you already use.

EDGE COMPUTE

Onboard processing

ATAK / CoT

Mission ready

ROS2 / MAVLink

Native support

STATUS

OPERATIONAL